

FIG. 1

10087400.030102

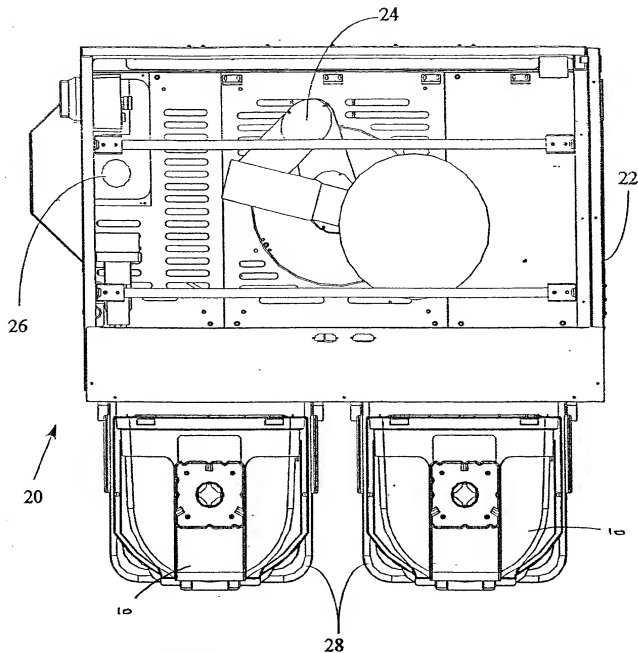


FIG. 2

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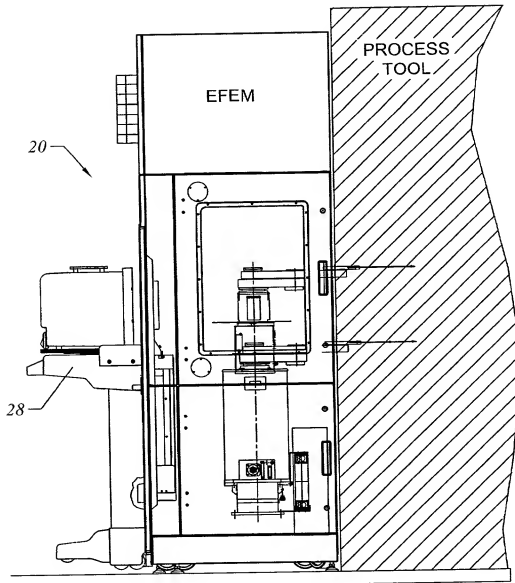
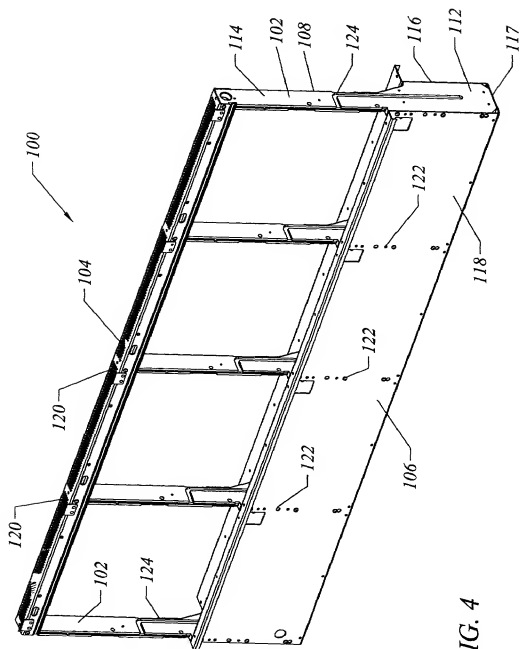


FIG. 3

1087400.030102



201209-00128007

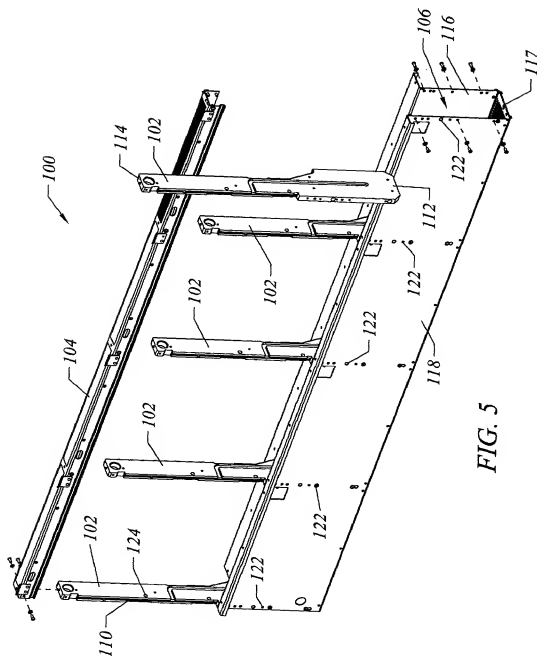


FIG. 5

2010ED-20475001

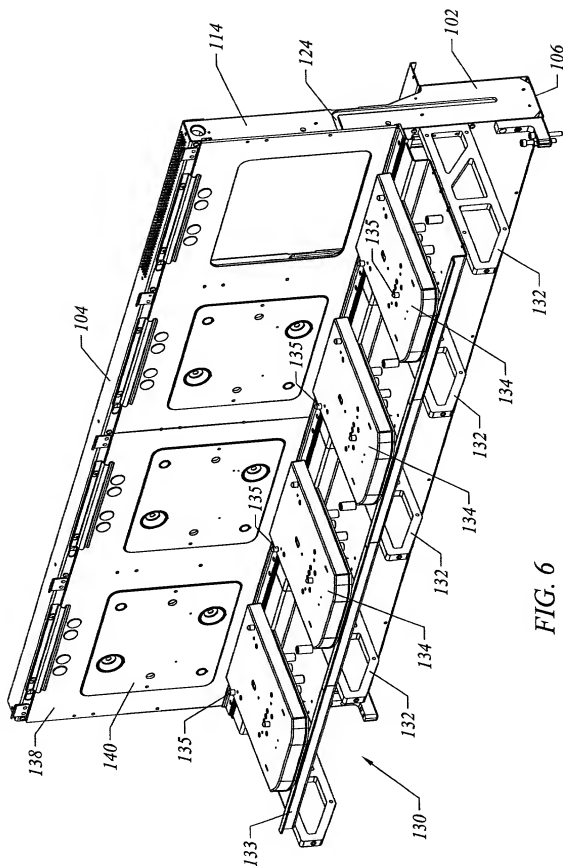


FIG. 6

2010020-00428001

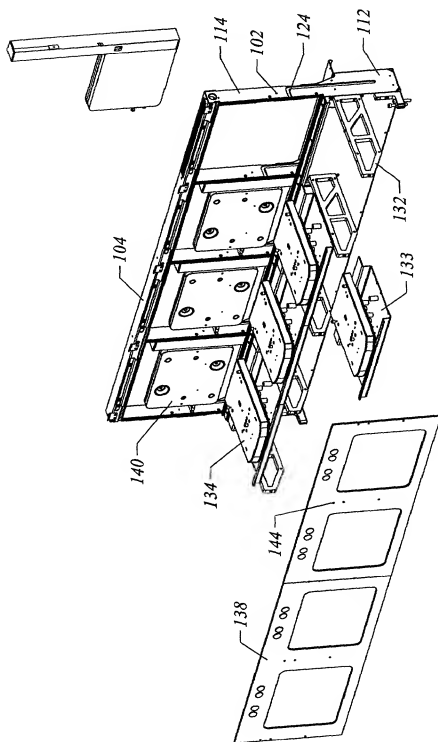
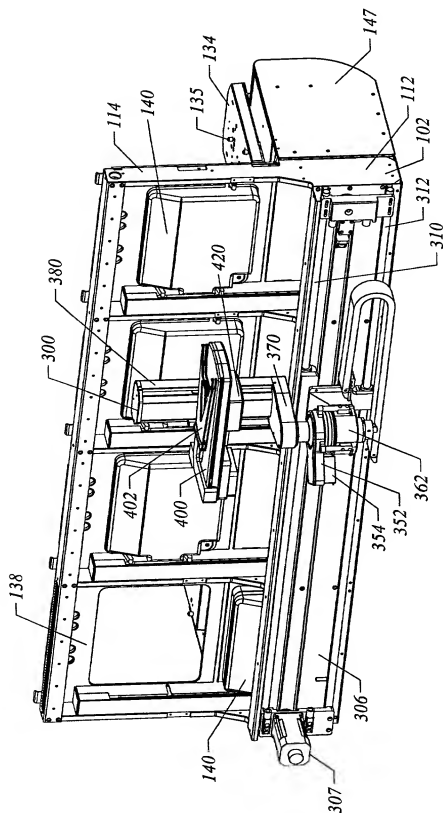


FIG. 7



201020-00428001

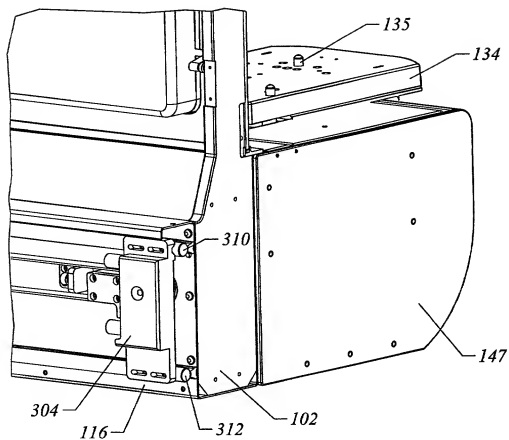


FIG. 9

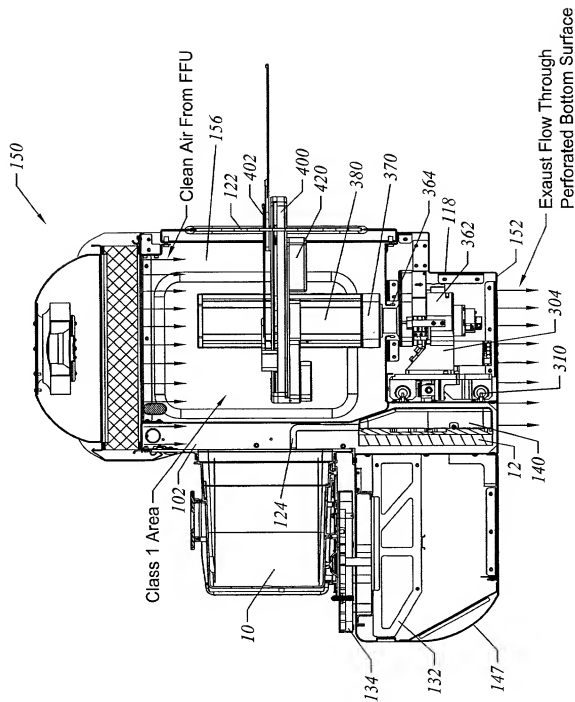


FIG. 10

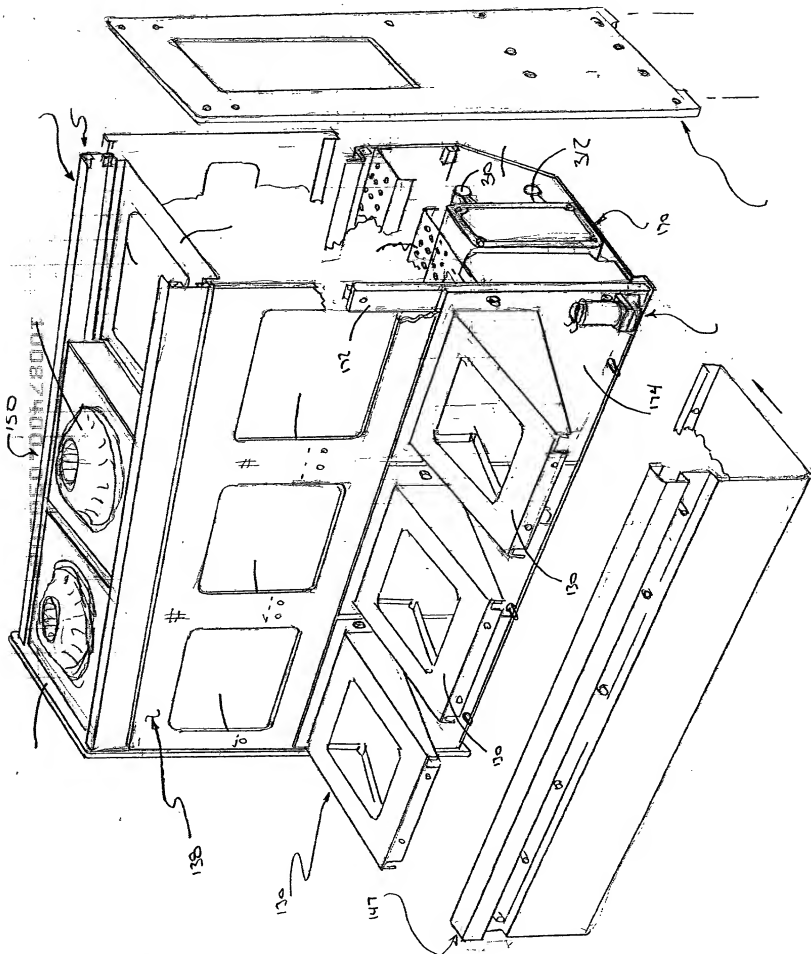


FIG. 11

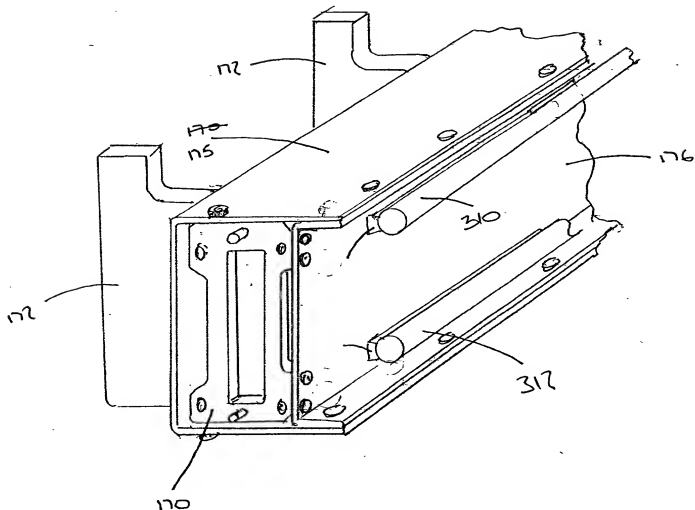


FIG. 13

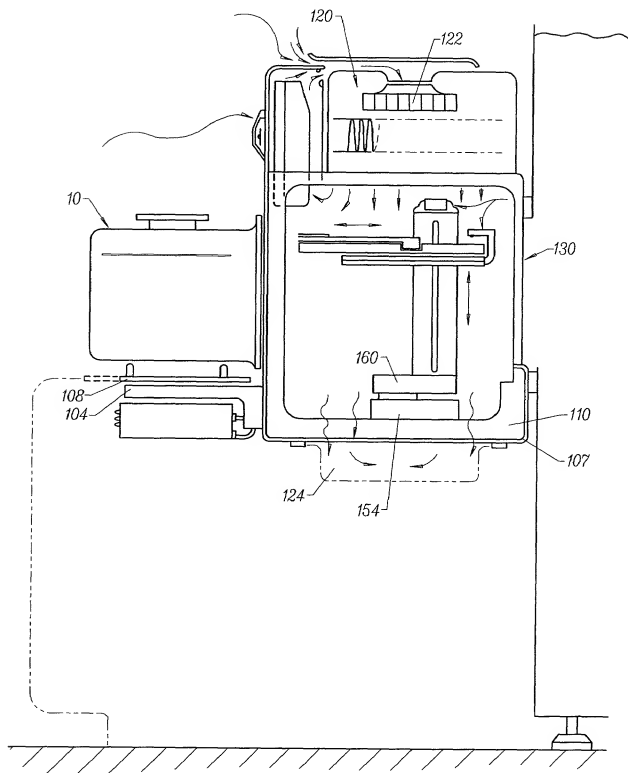


FIG. 15

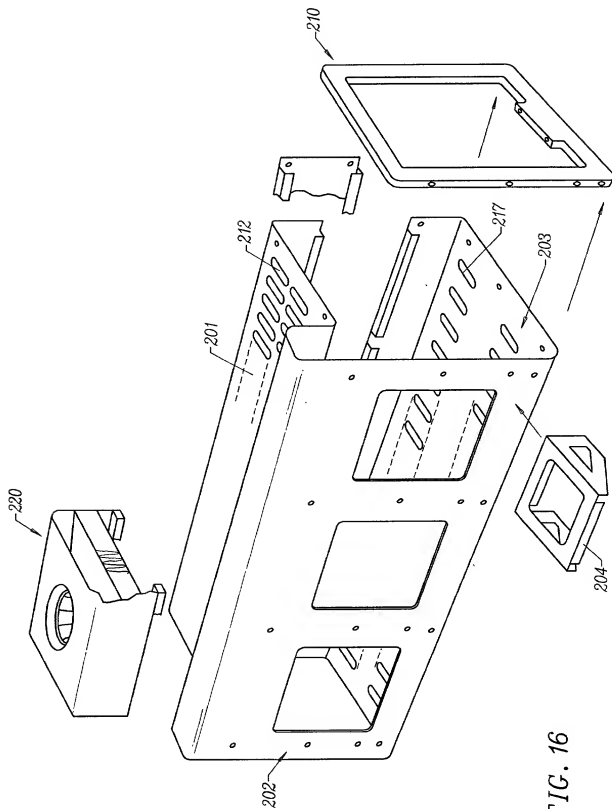


FIG. 16

201060*0042803

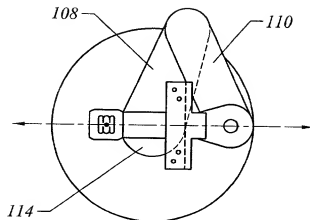


FIG. 17A
(Prior Art)

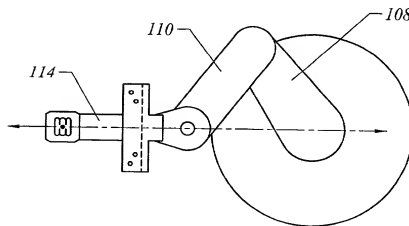


FIG. 17B
(Prior Art)

10087400.030102

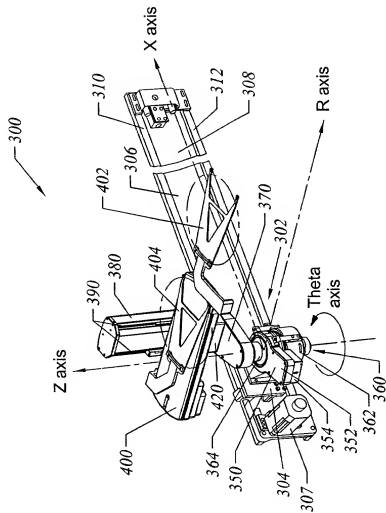


FIG. 18

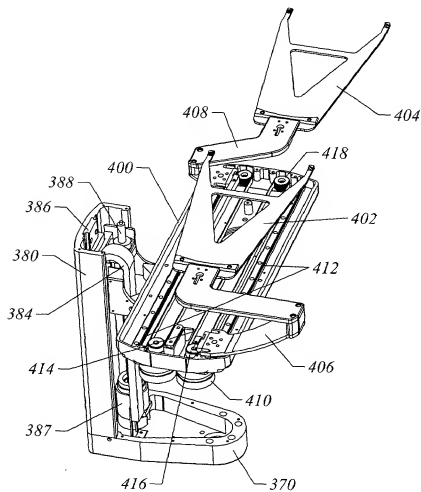


FIG. 19

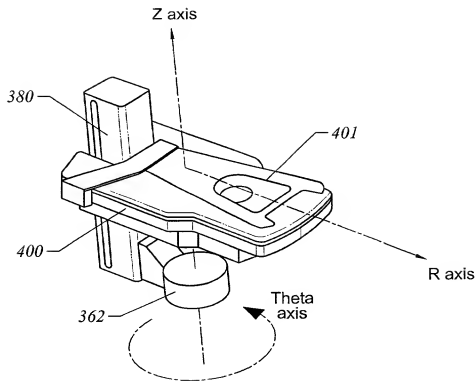


FIG. 20

207000-00428001

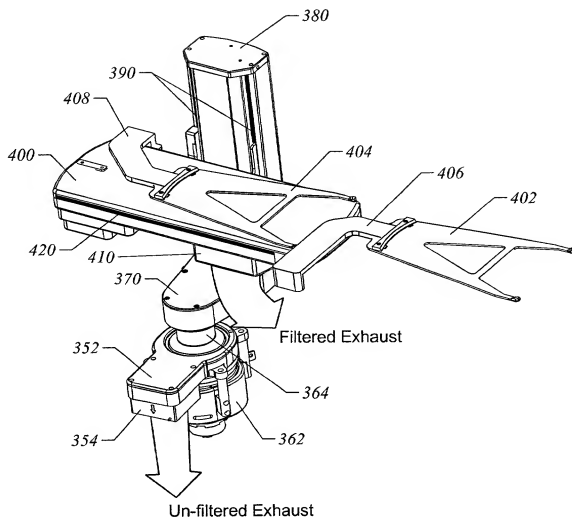


FIG. 21

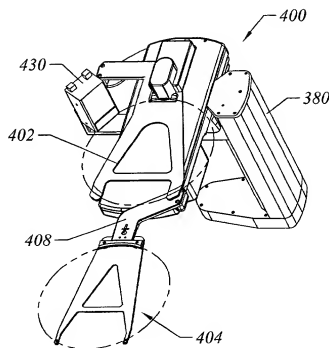


FIG. 22A

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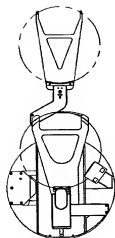


FIG. 22B

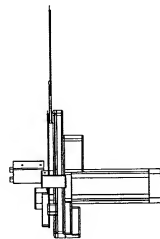


FIG. 22C

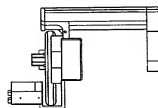


FIG. 22D

200000000428001

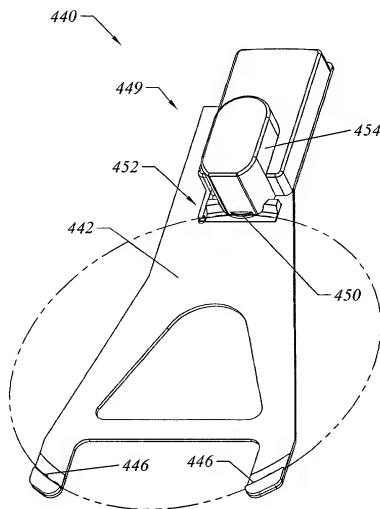


FIG. 23

10087400.030102

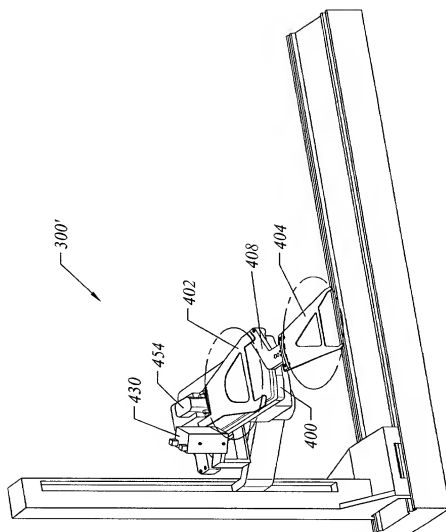
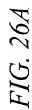
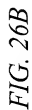


FIG. 25

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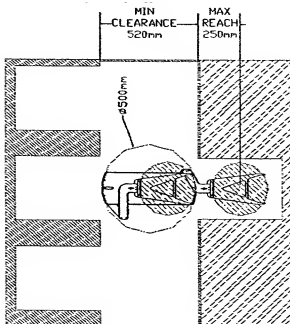
2070EO-004280Y

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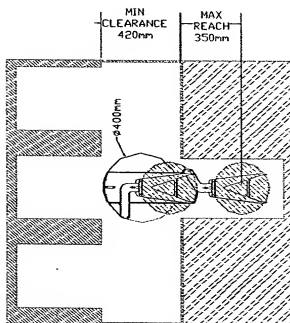
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Conventional Linear Slide Robot



FK.27A

Off-Center Slide-Body (50mm offset)



EFEM Process Tool

FK.27B

2010000047800T

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Example motion sequence for rapid swap slide-body with off center rotation axis.

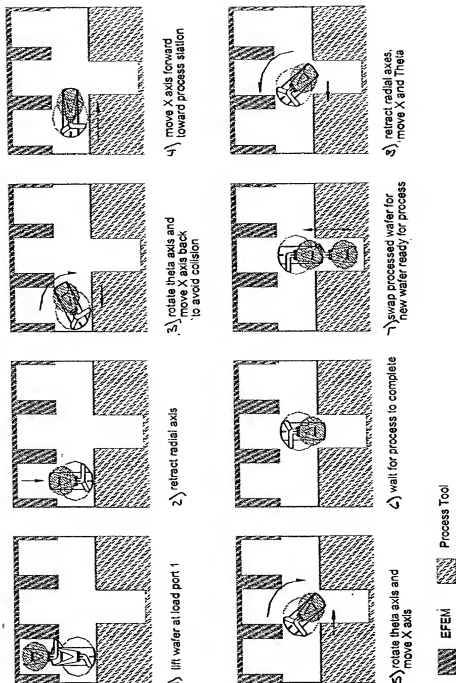


FIG. 28

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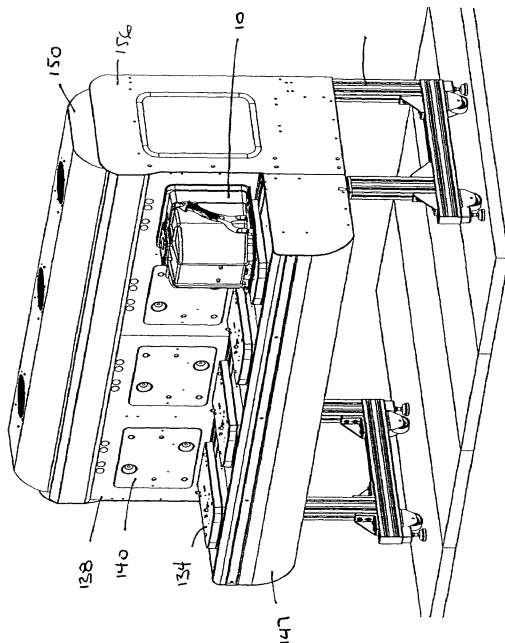


FIG. 29A

10087400.030102

207080-0042800T

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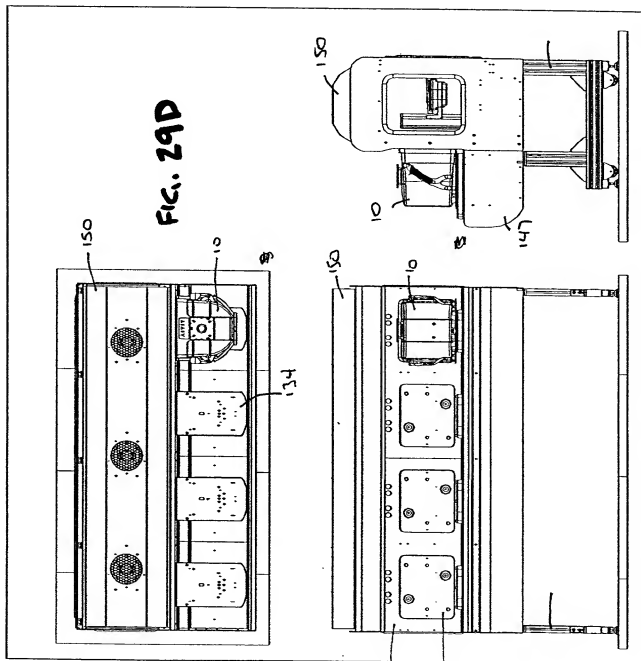


FIG. 29C

FIG. 29B

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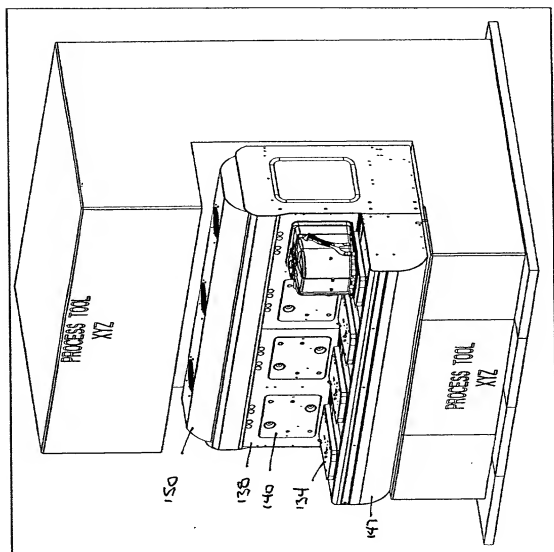


Fig. 30A

2070507 00478007

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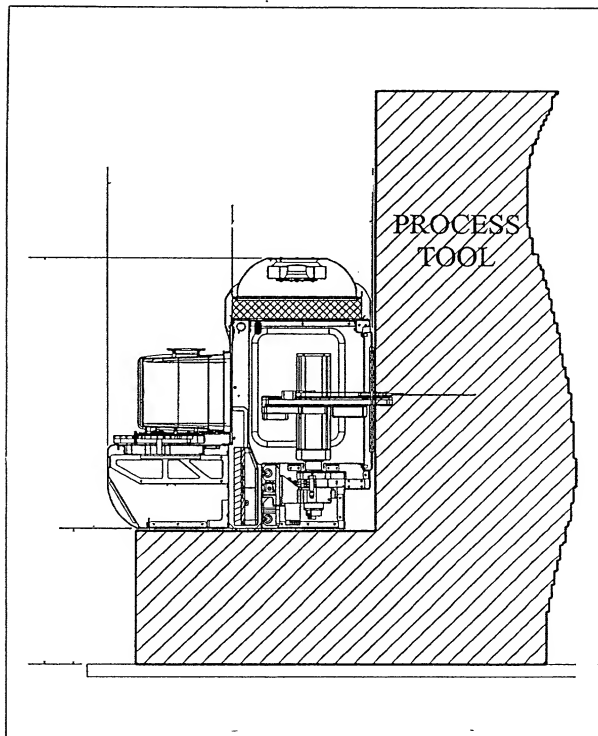


FIG. 30B

10087400.030102

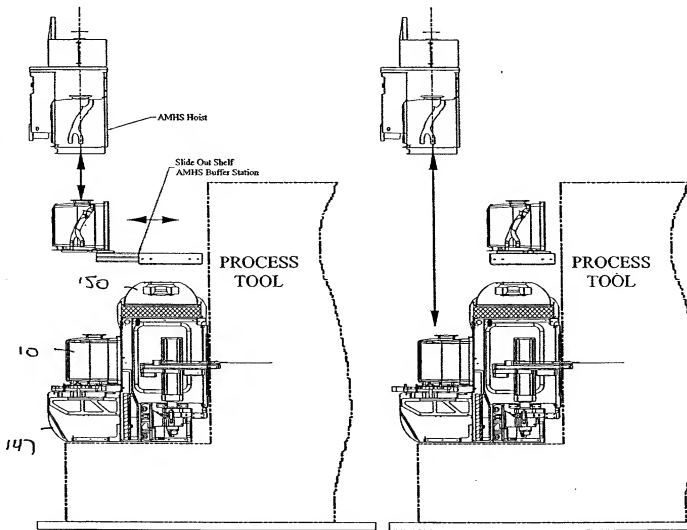


FIG. 31

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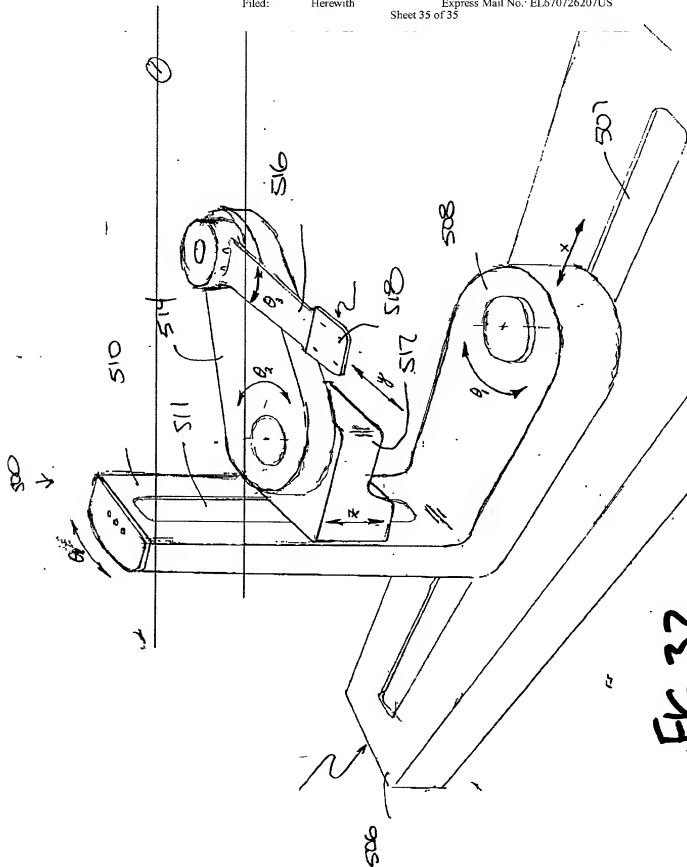


FIG. 32

10087400.030302